

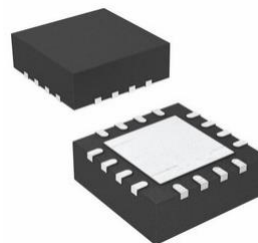
## Three Phase Sensorless Sinusoidal BLDC Driver

### PRODUCT DESCRIPTION

The MS37549 and MS37545 are three phase sensorless DC pre-drivers, adopting sinusoidal drive method. And the chip is characterized by low noise and small vibration.

Motor speed can be controlled by speed control pin. And power supply can be down to 4V to adjust the speed.

The MS37549 and the MS37545 are in QFN16 package with exposed thermal pad.



QFN16

### FEATURES

- 180° Sinusoidal Drive with Low Noise
- External PNMOS
- High-Frequency Control Algorithm
- Sensorless Control
- Analog Speed Control Input (MS37545)
- PWM Speed Control Input (MS37549)
- Sleep Mode
- FG Speed Feedback Output
- Lock Detection Function
- Overcurrent Protection
- Soft Start

### APPLICATIONS

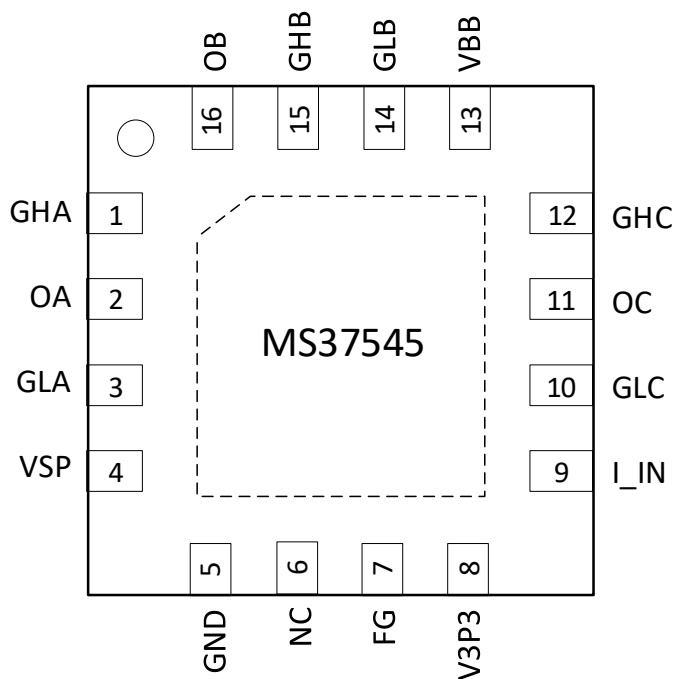
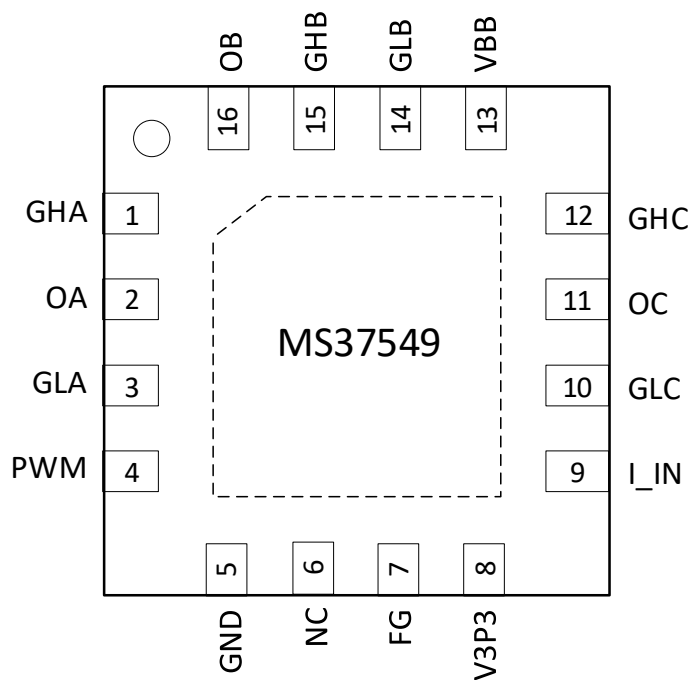
- Fan
- Consumption Type Product

### PRODUCT SPECIFICATION

Part Number	Package	Marking
MS37549	QFN16	MS37549
*MS37545	QFN16	MS37545

\*The package is not available temporarily. If necessary, please contact Hangzhou Ruimeng Sales Department Center.

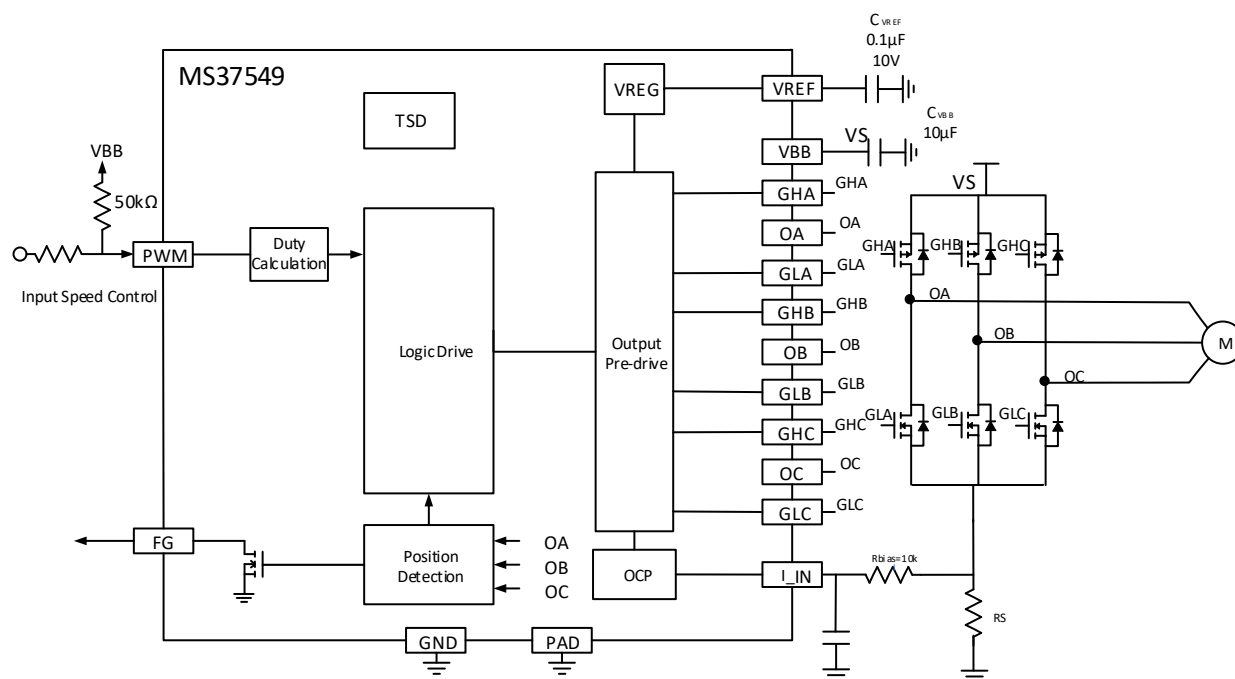
## PIN CONFIGURATION



## PIN DESCRIPTION

Pin	Name	Type	Description
1	GHA	O	High-side Gate Drive of Half Bridge A
2	OA	I	Output(A) of External Motor
3	GLA	O	Low-side Gate Drive of Half Bridge A
4	PWM	I	Speed Control Input (MS37549)
	VSP	I	Speed Control Input (MS37545)
5	GND	-	Ground
6	NC	-	Not Connect
7	FG	O	Speed Feedback Signal, Open-drain Output
8	V3P3	O	3.3V Output
9	I_IN	I	Current Detect Input
10	GLC	O	Low-side Gate Drive of Half Bridge C
11	OC	I	Output(C) of External Motor
12	GHC	O	High-side Gate Drive of Half Bridge C
13	VBB	-	Power Supply
14	GLB	O	Low-side Gate Drive of Half Bridge B
15	GHB	O	High-side Gate Drive of Half Bridge B
16	OB	I	Output(B) of External Motor

## BLOCK DIAGRAM



**ABSOLUTE MAXIMUM RATINGS**

Any exceeding absolute maximum rating application causes permanent damage to device. Because long-time absolute operation state affects device reliability. Absolute ratings just conclude from a series of extreme tests. It doesn't represent chip can operate normally in these extreme conditions.

Parameter	Symbol	Ratings	Unit
Supply Voltage	$V_{BB}$	30	V
Input Logic Voltage	$V_{IN}$	-0.3 ~ 6	V
FG Logic Output	$V_{FG}$	30	V
FG Logic Output Current	$I_{FG}$	10	mA
Operating Ambient Temperature	$T_A$	-40 ~ 125	°C
Storage Temperature	$T_{STG}$	-65 ~ 150	°C

## ELECTRICAL CHARACTERISTICS

Unless otherwise noted,  $T_A=25^{\circ}\text{C} \pm 2^{\circ}\text{C}$  and  $V_{BB}=12\text{V}$ .

### Power Dissipation

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Supply Voltage	$V_{BB}$		4		24	V
Supply Current	$I_{BB}$	Normal Operation, $V_{IN}=3\text{V}$		8	11	mA
Operating Current in Sleep Mode	$I_{STB}$			<1		$\mu\text{A}$

### Digital Input

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Input Current	$I_{IN}$	$V_{IN}=3\text{V}(R_{IN}=100\text{k}\Omega \text{ Pull-down})$		33		$\mu\text{A}$
Low-Level Input Voltage	$V_{IL}$				0.8	V
High-Level Input Voltage	$V_{IH}$		2			V
Logic Input Hysteresis	$V_{IHYS}$		200	300	600	mV
Input Pull-down Resistance	$R_{IN}$		50	100	200	$\text{k}\Omega$

### MS37549 Speed Control (PWM Pin)

Parameter	Symbol	Condition	Min	Typ	Max	Unit
PWM On-Threshold	$D_{ON}$		9.5	10	10.5	%
PWM Off-Threshold	$D_{OFF}$		7	7.5	8	%
PWM Input Frequency	$f_{PWM}$		0.1		100	kHz

### MS37545 Speed Control (VSP Pin)

Parameter	Symbol	Condition	Min	Typ	Max	Unit
VSP On-Threshold	$V_{ON}$			0.95		V
VSP On-Time	$t_{ON}$	$C_{VREF}=1\mu\text{F}$	100			$\mu\text{s}$
VSP Off-Threshold	$V_{THOFF}$			280		mV
VSP Accuracy	$E_{RRVSP}$			$\pm 6$		LSB
VSP Maximum Level	$V_{SP(MAX)}$			3.1		V

### Output Characteristics

Parameter	Symbol	Condition	Min	Typ	Max	Unit
High-side Gate Drive Voltage	$V_{GH}$			5		V
Low-side Gate Drive Voltage	$V_{GL}$			5.8		V
High-side Pull-up Current	$I_{GH\_PU}$			50		mA
Low-side Pull-up Current	$I_{GL\_PU}$			30		mA
High-side Pull-down Current	$I_{GH\_PD}$			50		mA
Low-side Pull-down Current	$I_{GL\_PD}$			30		mA

### Protection Circuit

Parameter	Symbol	Condition	Min	Typ	Max	Unit
VBB Undervoltage Lockout (UVLO)	$V_{BBUVLO}$	$V_{BB}$ Rise		3.7		V
VBB UVLO Hysteresis	$V_{BBUVHYS}$			200		mV
Lock Protection Time	$t_{OFF}$			8		s
Lock Detection Time	$t_{DETECT}$			1		s
I_IN Pin Pull Current	$I_{BIAS\_I\_IN}$			50		$\mu A$
Internal Current Limiting Reference Voltage	$V_{OLP}$			1		V
Internal OverCurrent Reference Voltage	$V_{OCP}$			1.5		V
Thermal Shutdown Temperature (TSD)	$T_{TSD}$	Temperature Rise		165		$^{\circ}C$
Thermal Shutdown Hysteresis	$T_{TSDHYS}$			20		$^{\circ}C$

## FUNCTION DESCRIPTIONS

The MS37545 and MS37549 can be applied to fan for the applications, which need low noise, small vibration and high frequency.

### Sleep Mode

The sleep mode of MS37549 is controlled by PWM pin. When the PWM input pin is lower than PWM Off-Threshold for more than 36ms, the chip will enter sleep mode. At this time, the power consumption is less than 1 $\mu$ A. When PWM input goes high, the chip will restart immediately.

The sleep mode of MS37545 is controlled by VSP pin. When the VSP input pin is lower than VSP Off-Threshold for more than 36ms, the chip will enter sleep mode. At this time, the dissipation is less than 1 $\mu$ A. When VSP input goes high, the chip will restart immediately.

### Speed Control

The fan speed is adjusted through three ways: voltage mode (control power supply), PWM duty cycle input control (MS37549) or analog input control (MS37545). The chip voltage in voltage mode can be decreased to 4V, to meet some specific applications.

#### MS37545-VSP Pin Analog Input Control

An internal ADC converts input voltage to a value required by speed control (Figure 1). When input voltage is less than  $V_{THOFF}$ , the motor outputs are disabled. However when starting, input must reach  $V_{THON}$  for  $t_{ON}$ . The  $t_{ON}$  delay time ensures normal startup of internal power reference and analog model. After the delay, VSP can control operation between  $V_{THOFF}$  and full-amplitude (7.5% - 100%). If 100% speed is needed, just directly connect a 50k $\Omega$  resistor between VSP pin and power supply.

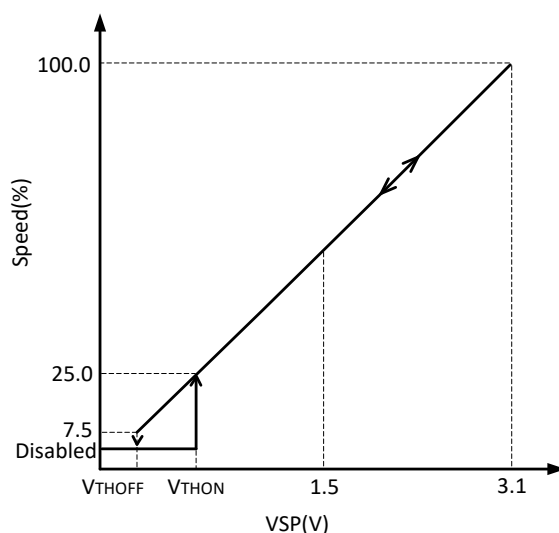


Figure 1. MS37545 Analog Speed Input Characteristic

#### MS37549-PWM Pin Duty Cycle Input Control

An internal PWM duty cycle measurement mode translates PWM input to required value (9-bit data) to control fan speed. When PWM duty cycle reaches about 10%, the motor drive will start working (Figure 2). PWM input terminal integrates filter to filter some interference signals, which may result in opening or closing chip.

PWM pin integrates a pull-down resistor (100k $\Omega$ ). And if input pin isn't good connection, the chip will disable output drive directly. If 100% speed is needed, just directly connect a 50k $\Omega$  resistor between PWM pin and power supply.



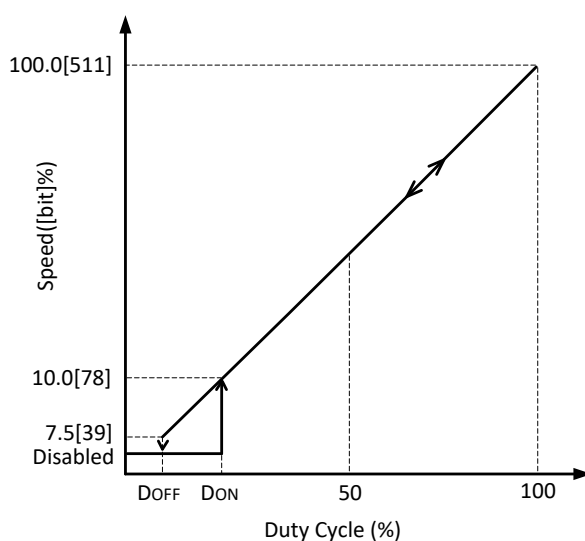


Figure 2. MS37549 PWM Speed Input Characteristic

### Power Supply Mode

The motor speed can be controlled by power supply voltage as well. Through the way, just need to connect a 50kΩ resistor between VBB pin and VSP pin (MS37545) or PWM pin (MS37549). The motor driver will be controlled by VBB Undervoltage Lockout. And it is enabled or disabled when power supply is above or under threshold.

### Lock Protection

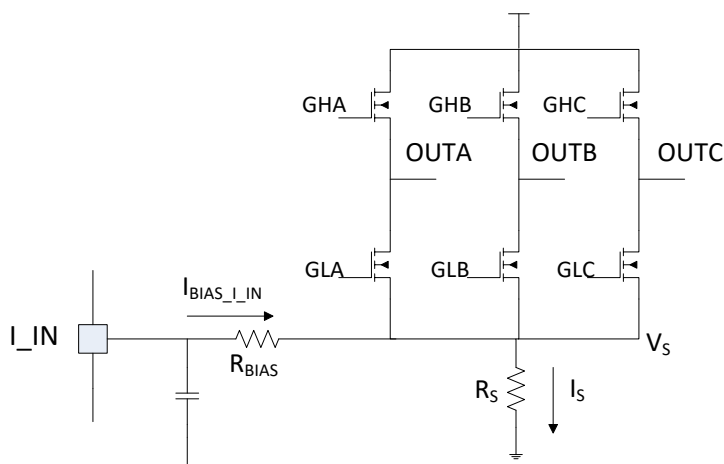
The chip detects current speed and judges whether it's in lock state. If a lock state is detected, the chip will disable drive for  $t_{OFF}$ , and try to restart motor after the time.

### FG

FG output is open-drain, used to indicate current speed condition. FG changes one period accordingly every time the motor rotates in a circle.

### Current Detection and Protection

$I_{IN}$  pin outputs 50μA current,  $R_{bias}$  is used for generating a DC reference to prevent negative voltage.



The relationship between  $V_{I\_IN}$  and  $I_S$  is shown in equation below:

$$V_{I\_IN} = I_{BIAS\_I\_IN} \times R_{BIAS} + I_S \times R_S$$

Recommend to add 0.5V DC offset on  $I_{I\_IN}$ . And  $R_{BIAS}$  can be 10k $\Omega$ .

Current Limiting function is set as follow. When detecting  $V_{I\_IN}$  exceeds internal current limiting reference voltage ( $V_{OLP}$ ), PMOS of this side would be off in remaining PWM period until next period start.  $V_{OLP}$  is set as 1V during normal operation.

When detecting  $V_{I\_IN}$  exceeds internal overcurrent reference voltage ( $V_{OCP}$ ), the chip would disable output directly.  $V_{OCP}$  is set as 1.5V during normal operation.

#### Soft Start

The soft start function needs to combined with current limiting protection. The reference voltage of current limiting protection can choose fast ramp and slow rape.

Fast Ramp, the reference voltage rises from 0.5V to 1V within 1s after startup.

Slow Ramp, the reference voltage rises from 0.5V to 1V within 4s after startup.

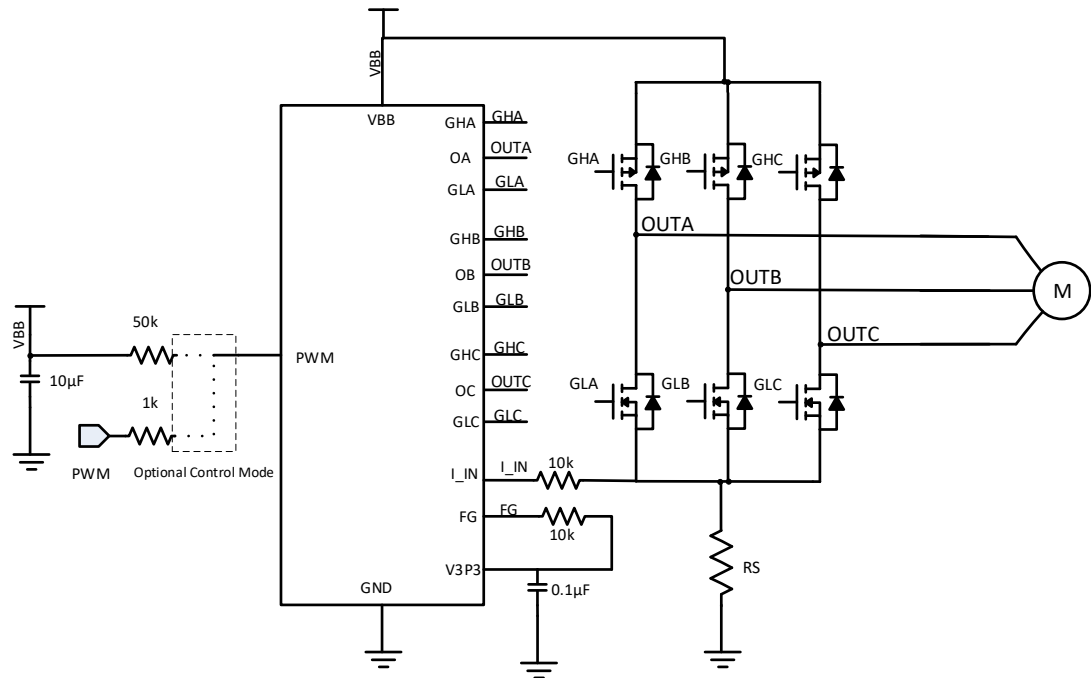
Combined with internal current limiting protection, only require to adjust  $R_S$  and  $R_{BIAS}$ , accordingly achieve an appropriate soft start process.

#### Protection Mode

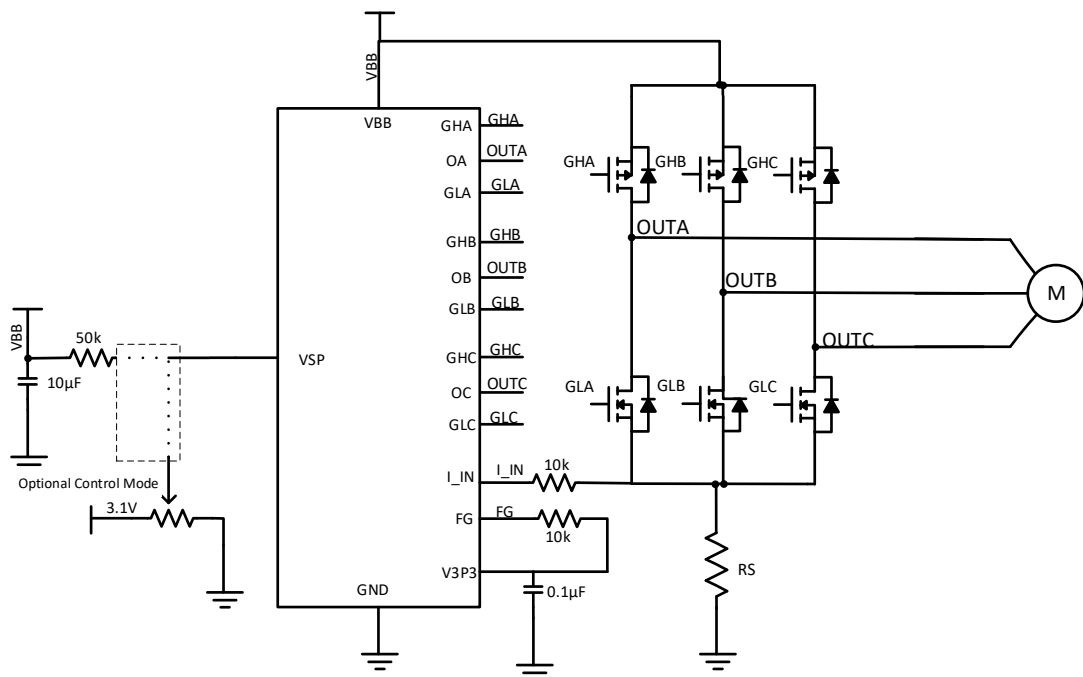
The chip has perfect protection mode: lock detection with restart, overcurrent protection, output short circuit protection, power supply undervoltage lockout and thermal shutdown.

TYPICAL APPLICATION DIAGRAM

MS37549

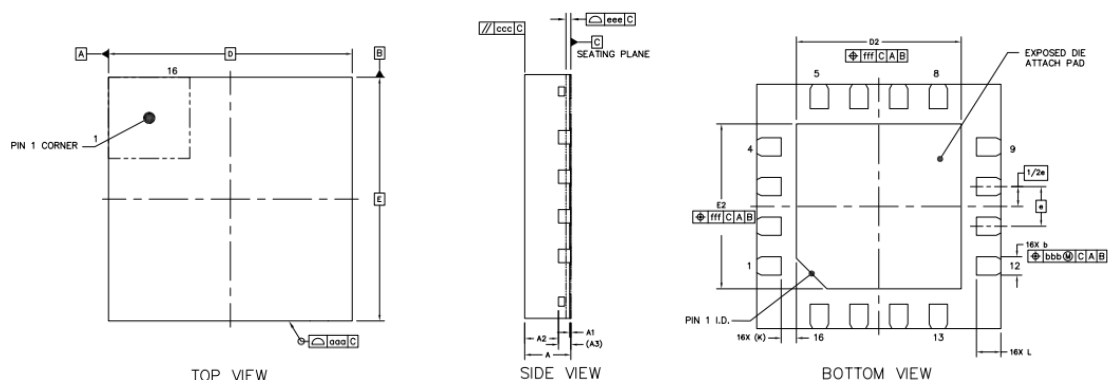


MS37545



# PACKAGE OUTLINE DIMENSIONS

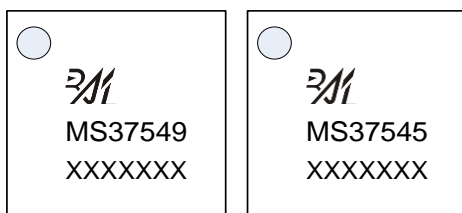
## QFN16



Symbol	Dimensions in Millimeters		
	Min	Typ	Max
A	0.7	0.75	0.8
A1	0.000	0.02	
A2		0.55	
A3	0.203REF		
b	0.25	0.3	0.35
D	4		
E	4		
e	0.65		
D2	2.6	2.7	2.8
E2	2.6	2.7	2.8
L	0.3	0.4	0.5
K	0.25REF		
aaa	0.1		
ccc	0.1		
eee	0.08		
bbb	0.1		
fff	0.1		

## MARKING and PACKAGING SPECIFICATION

### 1. Marking Drawing Description



Product Name: MS37549, MS37545

Product Code: XXXXXXX

### 2. Marking Drawing Demand

Laser printing, contents in the middle, font type Arial.

### 3. Packaging Specification

Device	Package	Piece/Reel	Reel/Box	Piece /Box	Box/Carton	Piece/Carton
MS37549	QFN16	4000	1	4000	8	32000
MS37545	QFN16	4000	1	4000	8	32000

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- The process of improving product is endless. And our company would sincerely provide more excellent product for customer.

**MOS CIRCUIT OPERATION PRECAUTIONS**

Static electricity can be generated in many places. The following precautions can be taken to effectively prevent the damage of MOS circuit caused by electrostatic discharge:

1. The operator shall ground through the anti-static wristband.
2. The equipment shell must be grounded.
3. The tools used in the assembly process must be grounded.
4. Must use conductor packaging or anti-static materials packaging or transportation.



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