

Unipolar Stepper Motor Driver

FEATURES

- Unipolar Stepper Motor Driver
- Integrated Clamp Diode
- STEP/DIR Control
- Under Well Heat Dissipation: Maximum Driving Current: 2A for Each Channel
- Power Supply: 7.2V~50V
- eTSSOP16 Package

APPLICATIONS

- Unipolar Stepper Motor

PRODUCT SPECIFICATION

Part Number	Package	Marking
MS31805TE	eTSSOP16	MS31805TE

PRODUCT DESCRIPTION

The MS31805TE is a unipolar stepper motor driver with overcurrent protection function. It integrates four-channel, low-side driver with overcurrent protection function. The MS31805TE integrates clamp diode to clamp the voltage generated by inductance load regeneration.

The MS31805TE integrates stepper driver and allows simple STEP/DIR control mode. It also supports three step modes: 2 phase (full step), 1-2 phase (1/2 step), 1 phase (Wave Drive).

The MS31805TE can provide up to 2A continuous current for each channel under well heat dissipation. When all channels are enabled, maximum 1A continuous current is available.

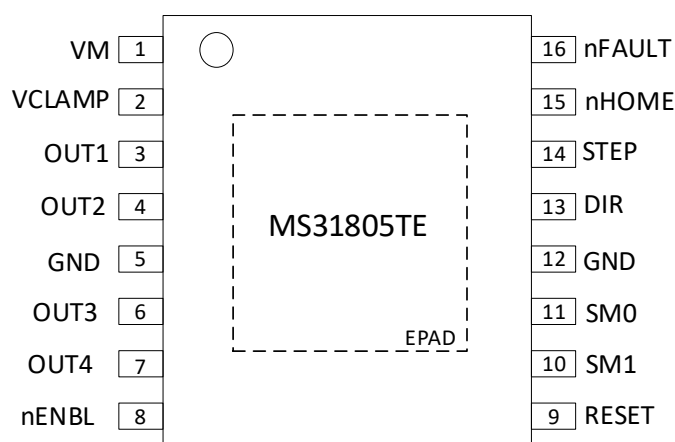
The integrated protection functions include undervoltage lockout, overcurrent protection, short-circuit protection and thermal shutdown. And the specific fault is indicated by fault output pin.

The MS31805TE is available in eTSSOP16 package.

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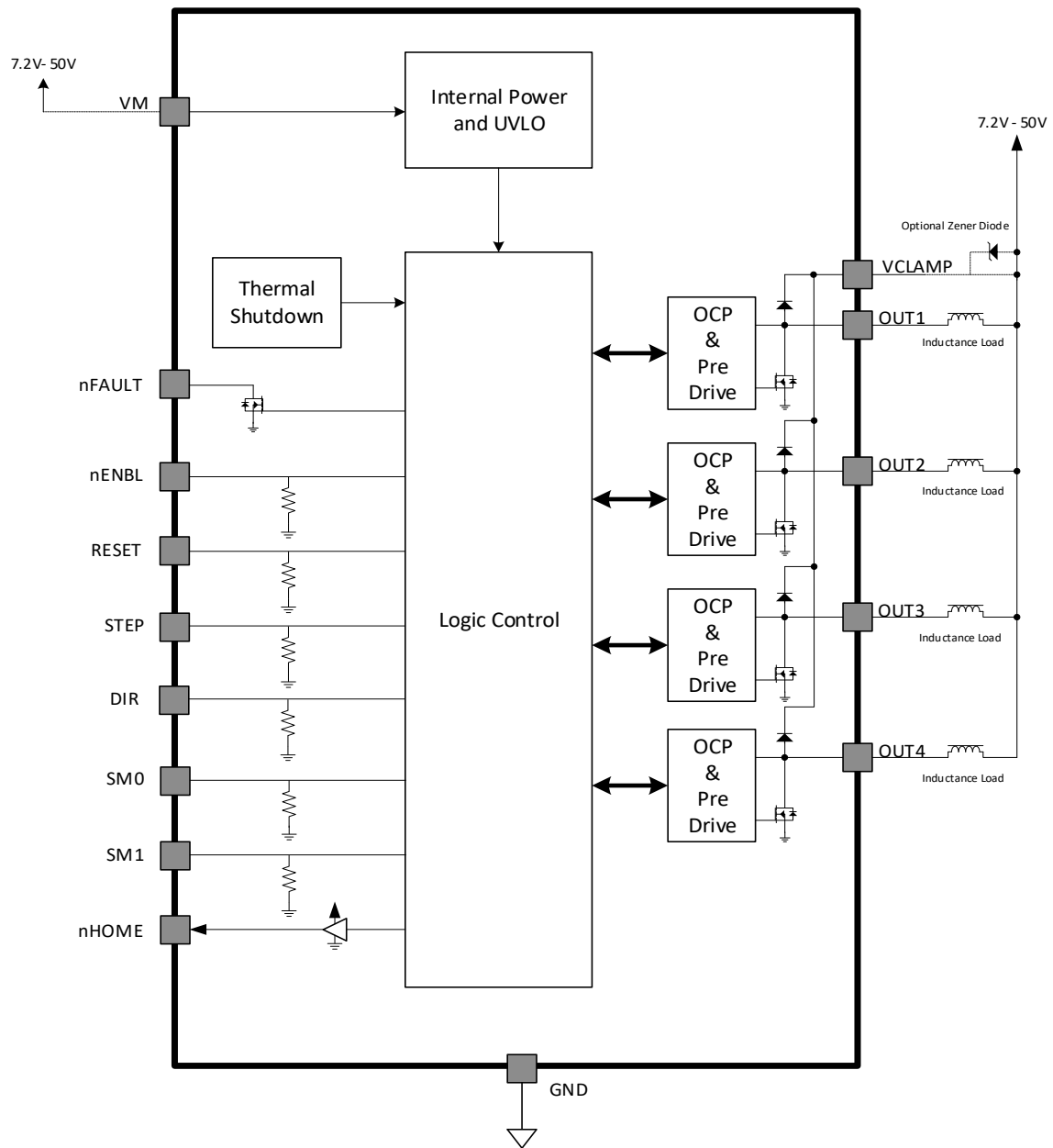
PIN CONFIGURATION



PIN DESCRIPTION

Pin	Name	Type	Description
1	VM	-	Power Supply, connected to motor power
2	VCLAMP	-	Output Clamp Voltage, connected to VM or by Zener diode
3	OUT1	O	Output 1
4	OUT2	O	Output 2
5	GND	-	Ground
6	OUT3	O	Output 3
7	OUT4	O	Output 4
8	nENBL	I	Enable Input, Low Active. Internal 100kΩ Pull-down Resistor
9	RESET	I	Reset Input. Reset internal logic and OCP when it is high-level. Internal 100kΩ Pull-down Resistor
10	SM1	I	SM1:SM0: Set Step Mode
11	SM0	I	00: 2 Phase (Full Step) 01: 1-2 Phase (1/2 Step) 10: 1 Phase (Wave Drive) 11: Reserved
12	GND	-	Ground
13	DIR	I	Direction Control Signal. Internal 100kΩ Pull-down Resistor
14	STEP	I	Step Signal, Rising Edge Active. Internal 100kΩ Pull-down Resistor
15	nHOME	OD	Output 0 when motor is located in initial position
16	nFAULT	OD	Fault Indication. Low-level when fault occurs
-	EPAD	-	Thermal Pad, recommended to ground

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Any exceeding absolute maximum rating application causes permanent damage to device. Because long-time absolute operation state affects device reliability. Absolute ratings just conclude from a series of extreme tests. It doesn't represent chip can operate normally in these extreme conditions.

Parameter	Symbol	Ratings	Unit
Power Supply	V_M	-0.3 ~ 55	V
	V_{CLAMP}	-0.3 ~ 55	V
V_{OUTx}	V_{OUTx}	-0.3 ~ 55	V
Digital Input Voltage	$V_{INRANGE}$	-0.3 ~ 5.5	V
Digital Output Voltage	$V_{OUTRANGE}$	-0.3 ~ 5.5	V
Peak Clamp Diode Current	I_{PD}	2	A
RMS Clamp Diode Current	I_{RMSPD}	1	A
Open-drain Output Current	I_{OD}	0 ~ 20	mA
Open-drain Output Voltage	V_{OD}	-0.3 ~ 5.5	V
Junction Temperature	T_J	-40 ~ 150	°C
Storage Temperature	T_{STG}	-65 ~ +150	°C
ESD(HBM)	V_{ESD}	±8k	V

RECOMMENDED OPERATING CONDITIONS

Parameter		Symbol	Range			Unit
			Min	Typ	Max	
Power Supply		V_M	7.2		50	V
		V_{CLAMP}	0		50	V
Output Current	(Single Channel On)	I_{OUT}			2	A
	(Four Channels On)				1	A

ELECTRICAL CHARACTERISTICS

Within power supply and operating temperature ranges. The operating conditions are $V_M=24V$ and $T_A=25^\circ C$ for all typical values.

Power Supply

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Power Supply Current	I_{VM}			1.6		mA
Undervoltage Lockout	V_{UVLO}	V_M rising			7	V

Logic Input

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Input Low-level Voltage	V_{IL}	No load			0.7	V
Input High-level Voltage	V_{IH}	No load	2			V
Input Hysteresis	V_{HYS}	No load		0.3		V
Input Low-level Current	I_{IL}	$V_{IN} = 0V$, No load	-20		20	μA
Input High-level Current	I_{IH}	$V_{IN} = 3.3V$, No load			100	μA
Pull-down Resistor	R_{PD}			100		k Ω

nFAULT Open-drain Output

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Output Low-level Voltage	V_{OL}	$I_O = 5mA$			0.4	V
Output Leakage Current	I_{OH}	$V_O = 3.3V$			1	μA

nHOME Output

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Output Low-level Voltage	V_{OL}	$I_O = 5mA$			0.5	V
Output High-level Voltage	V_{OH}	$V_M = 24V$		4.7		V
Output Source Current	I_{SOURCE}	$V_M = 24V$			1	mA
Output Sink Current	I_{SINK}	$V_M = 24V$			5	mA

Low-side MOS

Parameter	Symbol	Condition	Min	Typ	Max	Unit
On-Resistance	$R_{DS(on)}$	$V_M = 24V, I_O = 700mA, T_J = 25^\circ C$		420	700	m Ω
		$V_M = 24V, I_O = 700mA, T_J = 85^\circ C$		550	800	m Ω
		$V_M = 24V, I_O = 700mA, T_J = 125^\circ C$		650	950	m Ω
Output Leakage Current	I_{OFF}		-50		50	μA

Regeneration Diode

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Forward Voltage	V_F	$V_M = 24V, I_O = 700mA, T_J = 25^\circ C$		0.9		V
Reverse Leakage Current	I_R	$V_M = 24V, T_J = 25^\circ C$	-50		50	μA

Output

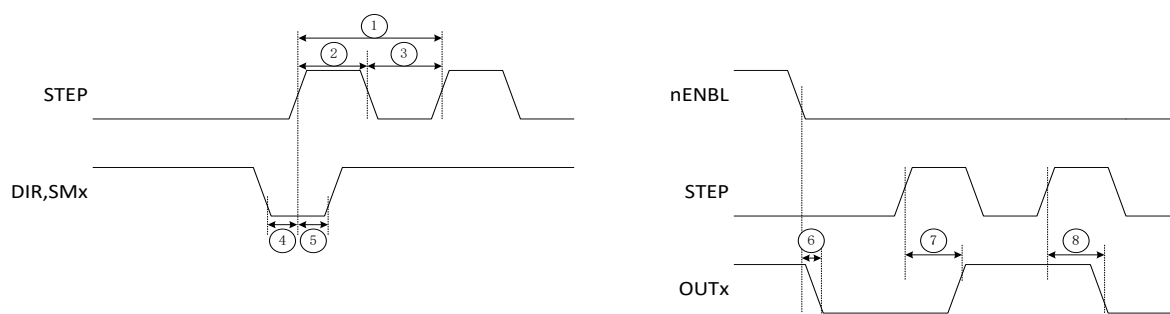
Parameter	Symbol	Condition	Min	Typ	Max	Unit
Rise Time	t_R	$V_M = 24V, I_O = 700mA, T_J = 25^\circ C, \text{Resistive load}$	50		300	ns
Fall Time	t_F	$V_M = 24V, I_O = 700mA, T_J = 25^\circ C, \text{Resistive load}$	50		300	ns
Maximum Switch Frequency	f_{chop}				500	kHz

Protection Circuit

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Overcurrent Protection Point	I_{OCP}		2.2	2.7	4	A
Overcurrent Protection Detection Time	t_{OCP}			3.6		μs
Overcurrent Protection Retry Time	t_{RETRY}			1.2		ms
Thermal Shutdown Point	T_{TSD}	Temperature rising	145	160	175	$^\circ C$

Timing

Number	Parameter	Symbol	Min	Typ	Max	Unit
1	STEP Frequency	f_{STEP}			250	kHz
2	STEP High Time	$t_{WH(STEP)}$	1.9			μs
3	STEP Low Time	$t_{WL(STEP)}$	1.9			μs
4	Setup Time, DIR or SMx to STEP	$t_{SU(STEP)}$	1			μs
5	Hold Time, DIR or SMx to STEP	$t_{H(STEP)}$	1			μs
6	Enable Time, nENBL to Output	$t_{OE(ENABLE)}$			50	μs
7	Delay Time, STEP Enable Output Low to High	$t_{PD(L-H)}$			500	μs
8	Delay Time, STEP Enable Output High to Low	$t_{PD(H-L)}$			500	μs
-	RESET Pulse Width	t_{RESET}	20			μs



TYPICAL CHARACTERISTICS CURVES

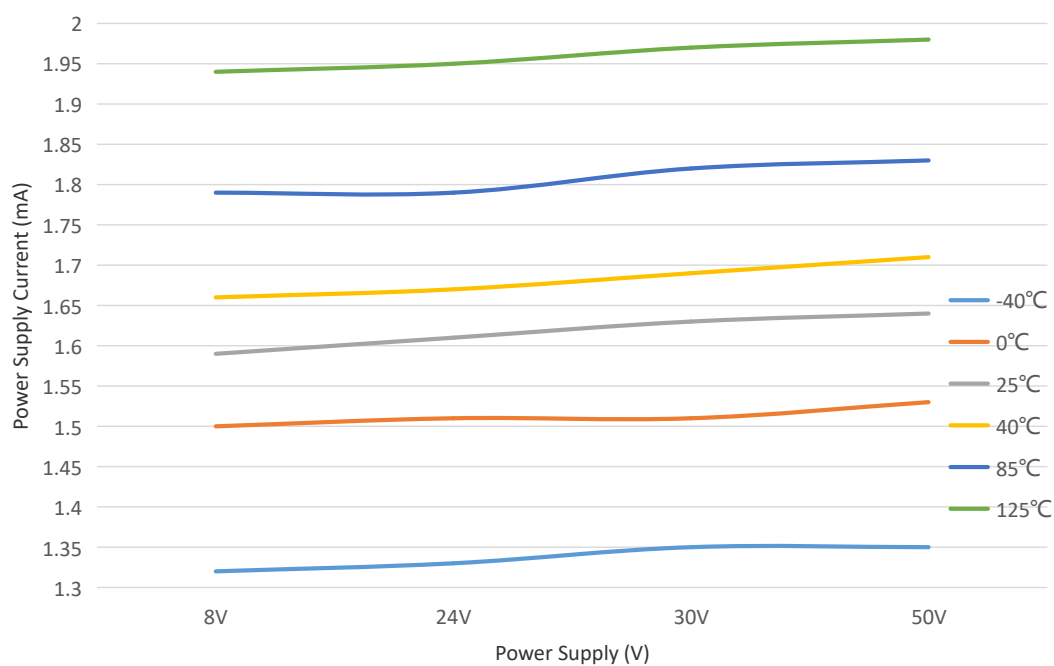


Figure 1. Power Supply Current VS. Power Supply

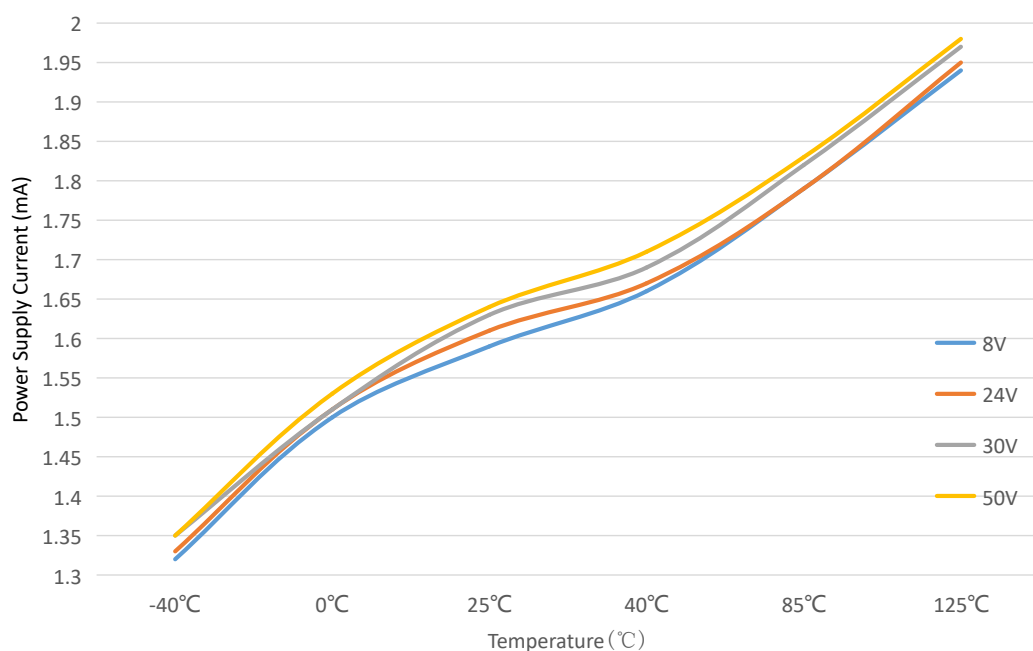


Figure 2. Power Supply Current VS. Temperature

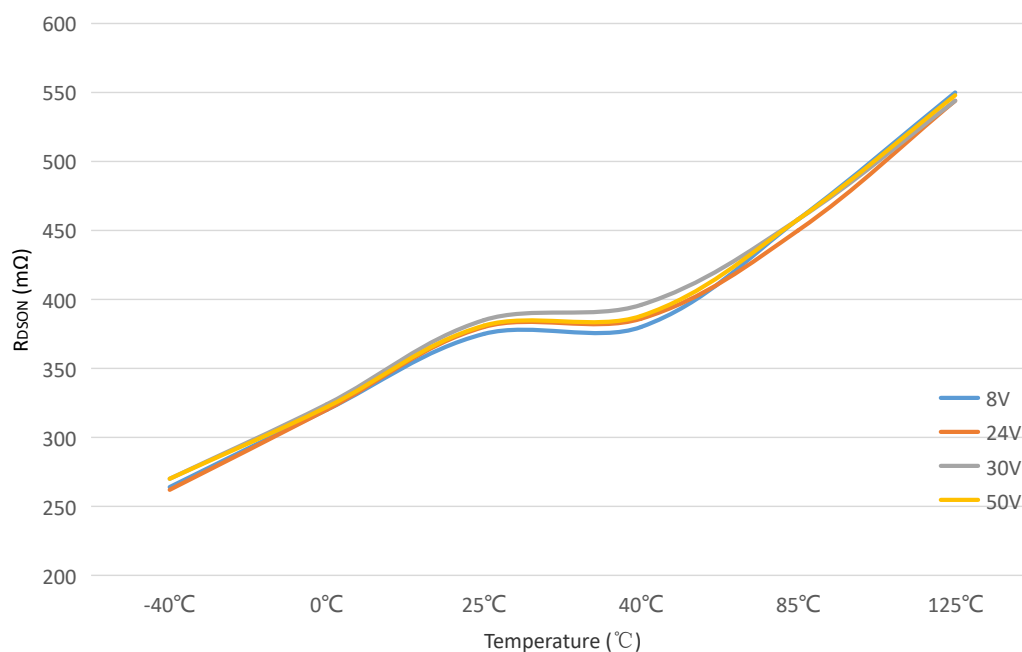


Figure 3. $R_{DS(on)}$ VS. Temperature

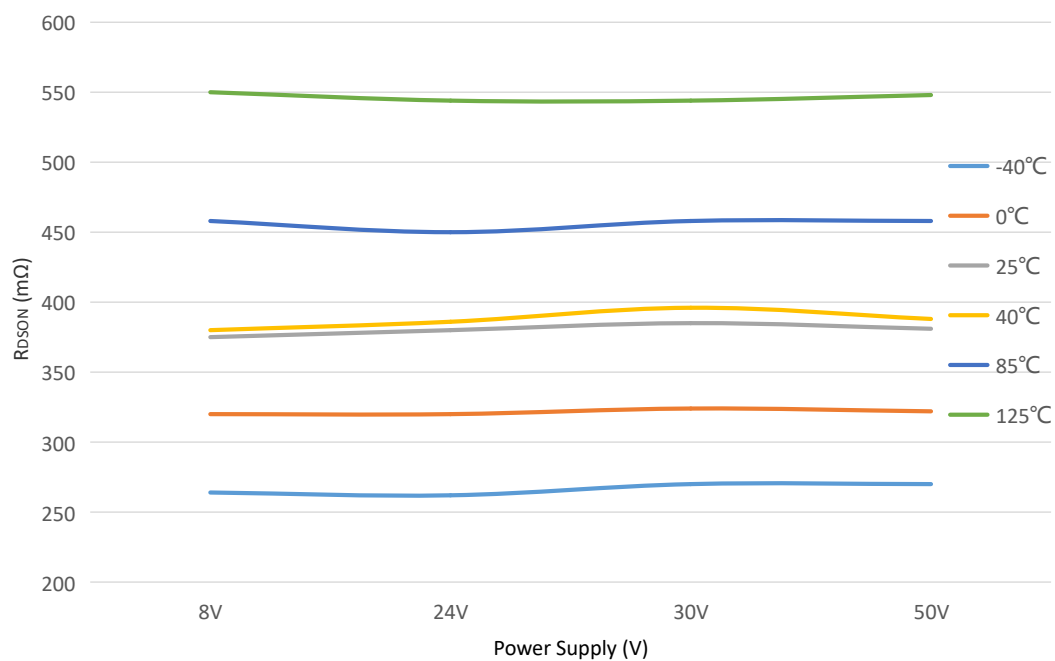


Figure 4. $R_{DS(on)}$ VS. Power Supply

FUNCTION DESCRIPTION

1. Overview

The MS31805TE is a unipolar stepper motor driver. The MS31805TE can be controlled by STEP/DIR interface. And different microstep modes are controlled by SM0 and SM1 interface.

The MS31805TE integrates clamp diode to clamp the voltage generated by inductance load regeneration.

The integrated protection functions include undervoltage lockout, overcurrent protection, short-circuit protection and thermal shutdown.

2. Output Driver

The MS31805TE includes four low-side drivers with protection functions. Each output integrates a clamp diode, which is connected to common pin, VCLAMP.

VCLAMP can be connected to VM. It can also be connected to a Zener or TVS diode to VM, allowing the switch voltage to exceed VM. Thus it can be beneficial to drive loads requiring fast decay, such as unipolar stepper motor.

Output voltage cannot exceed the maximum output voltage limit.

3. Protection Circuit

The MS31805TE has protection functions: undervoltage lockout, overcurrent protection and thermal shutdown. When these functions are triggered, shutdown operation is performed to protect the chip and motor.

3.1 Undervoltage Lockout

When VM pin voltage is less than undervoltage lockout threshold, all channels of the MS31805TE are disabled and internal logic is reset. When VM rises to above ULVO, the MS31805TE will recover normal operation.

3.2 Overcurrent Protection

Overcurrent protections on all output drivers limit the driving current by disabling the gate drive. If overcurrent limit time exceeds t_{OCP} (approximately $3.6\mu s$), the output will be disabled and the nFAULT pin will be pulled low. The driver will remain disabled within t_{RETRY} (approximately $1.2ms$).

Current recoveries and the fault will be automatically removed after t_{RETRY} . If RESET pin is activated or VM is reset, the fault will be removed immediately.

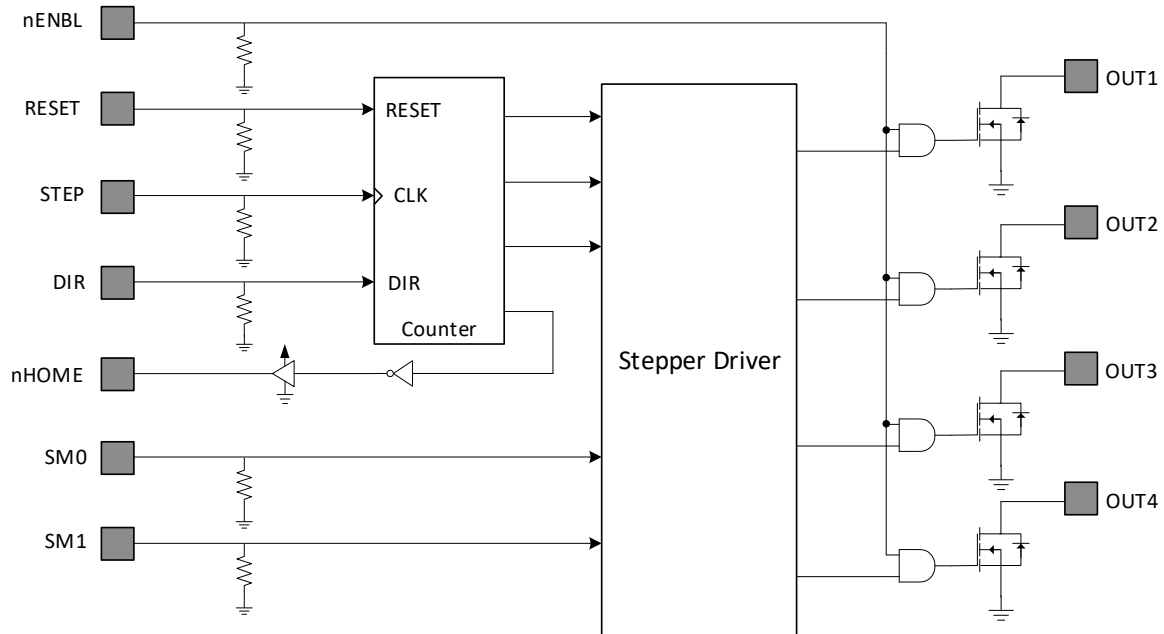
3.3 Thermal Shutdown

When chip temperature exceeds temperature limit, thermal shutdown is triggered, output is off and fault indication pin is pulled down. If chip temperature is normal, the fault is automatically removed and operation is recovered.

4. Function Description

4.1 Stepper Driver

The MS31805TE integrates a stepper driver and allows simple STEP/DIR control. Different step modes are selected by SM0 and SM1 interface.

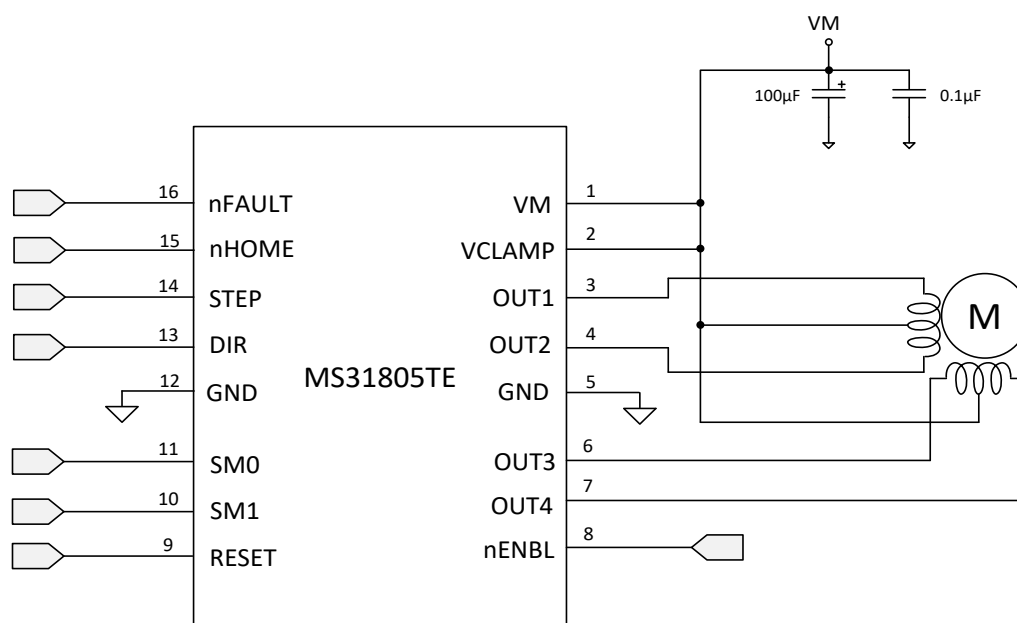


4.2 nENBL and Reset Operation

nENBL pin can enable or disable output driver. Driver can only be enabled when nENBL must be low. nENBL pin contains a pull-down resistor. When nENBL is high-level, internal logic is reset and all inputs are ignored. The MS31805TE provides automatic power-up reset function internally. No operation is performed on RESET pin when power-up.

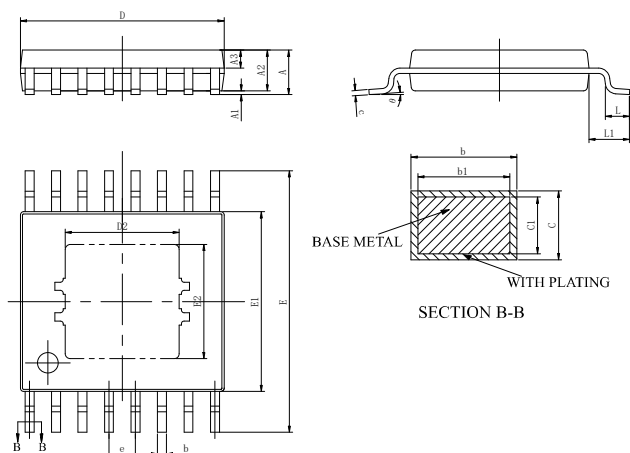
TYPICAL APPLICATION DIAGRAM

The typical application is for driving unipolar stepper motor as follows.



PACKAGE OUTLINE DIMENSIONS

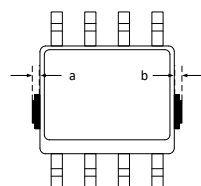
eTSSOP16



Symbol	Dimensions in Millimeters		
	Min	Typ	Max
A	-	-	1.20
A1	0.00	-	0.15
A2	0.90	1.00	1.05
A3	0.39	0.44	0.49
b	0.20	-	0.28
b1	0.19	0.22	0.25
c	0.13	-	0.17
c1	0.12	0.13	0.14
D	4.90	5.00	5.10
E	6.20	6.40	6.60
E1	4.30	4.40	4.50
e	0.65 BSC		
D2	2.80 REF		
L	0.45	-	0.75
L1	1.00 BSC		
θ	0	-	8°
E2	2.10 REF		

Note: In addition to the package size, a and b are allowed to have the maximum size of 0.15mm for waste glue simultaneously.

The diagram is as follows: taking SOP8 package as an example.



MARKING and PACKAGING SPECIFICATION

1. Marking Drawing Description



Product Name : MS31805TE

Product Code : XXXXXXX

2. Marking Drawing Demand

Laser printing, contents in the middle, font type Arial.

3. Packaging Specification

Device	Package	Piece/Reel	Reel/Box	Piece /Box	Box/Carton	Piece/Carton
MS31805TE	eTSSOP16	3000	1	3000	8	24000

STATEMENT

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- The process of improving product is endless. And our company would sincerely provide more excellent product for customer.

**MOS CIRCUIT OPERATION PRECAUTIONS**

Static electricity can be generated in many places. The following precautions can be taken to effectively prevent the damage of MOS circuit caused by electrostatic discharge:

1. The operator shall ground through the anti-static wristband.
2. The equipment shell must be grounded.
3. The tools used in the assembly process must be grounded.
4. Must use conductor packaging or anti-static materials packaging or transportation.



+86-571-89966911



Rm701, No.9 Building, No. 1 WeiYe Road, Puyan Street, Binjiang District, Hangzhou, Zhejiang



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